

RESEARCH

Open Access

A Pata-type fixed point theorem in modular spaces with application

Mohadeseh Paknazar^{1*}, Madjid Eshaghi², Yeol Je Cho³ and Seyed Mansour Vaezpour⁴

*Correspondence:

m.paknazar@yahoo.com

¹Department of Mathematics,
Science and Research Branch,
Islamic Azad University, Tehran, Iran
Full list of author information is
available at the end of the article

Abstract

In this paper, we present a Pata-type fixed point theorem in modular spaces which generalizes and improves some old results. As an application, we study the existence of solutions of integral equations in modular function spaces.

MSC: Primary 47H10; secondary 46A80; 45G10

Keywords: fixed point; modular spaces; nonlinear integral equations

1 Introduction and preliminaries

In 1950 Nakano [1] introduced the theory of modular spaces in connection with the theory of ordered spaces. Musielak and Orlicz [2] in 1959 redefined and generalized it to obtain a generalization of the classical function spaces L^p . Khamsi *et al.* [3] investigated the fixed point results in modular function spaces. There exists an extensive literature on the topic of the fixed point theory in modular spaces (see, for instance, [4–14]) and the papers referenced there.

Recently, Pata [15] improved the Banach principle. Using the idea of Pata, we prove a fixed point theorem in modular spaces. Then we show how our results generalize old ones. Also, we prepare an application of our main results to the existence of solutions of integral equations in Musielak-Orlicz spaces.

In the first place, we recall some basic notions and facts about modular spaces.

Definition 1.1 Let X be an arbitrary vector space over K ($= \mathbb{R}$ or \mathbb{C}).

- (a) A function $\rho : X \rightarrow [0, +\infty]$ is called a modular if
 - (i) $\rho(x) = 0$ if and only if $x = 0$;
 - (ii) $\rho(\alpha x) = \rho(x)$ for every scalar α with $|\alpha| = 1$;
 - (iii) $\rho(\alpha x + \beta y) \leq \rho(x) + \rho(y)$ if $\alpha + \beta = 1$ and $\alpha \geq 0, \beta \geq 0$ for all $x, y \in X$.
- (b) If (iii) is replaced by
 - (iv) $\rho(\alpha x + \beta y) \leq \alpha\rho(x) + \beta\rho(y)$ if $\alpha + \beta = 1$ and $\alpha \geq 0, \beta \geq 0$, we say that ρ is convex modular.
- (c) A modular ρ defines a corresponding modular space, *i.e.*, the vector space X_ρ given by

$$X_\rho = \{x \in X : \rho(\lambda x) \rightarrow 0 \text{ as } \lambda \rightarrow 0\}.$$

Example 1.2 Let $(X, \|\cdot\|)$ be a norm space, then $\|\cdot\|$ is a convex modular on X . But the converse is not true.

In general the modular ρ does not behave as a norm or a distance because it is not subadditive. But one can associate to a modular the F -norm (see [16]).

Definition 1.3 The modular space X_ρ can be equipped with the F -norm defined by

$$|x|_\rho = \inf \left\{ \alpha > 0; \rho \left(\frac{x}{\alpha} \right) \leq \alpha \right\}.$$

Namely, if ρ is convex, then the functional

$$\|x\|_\rho = \inf \left\{ \alpha > 0; \rho \left(\frac{x}{\alpha} \right) \leq 1 \right\},$$

is a norm called the Luxemburg norm in X_ρ which is equivalent to the F -norm $|\cdot|_\rho$.

Definition 1.4 Let X_ρ be a modular space.

- (a) A sequence $\{x_n\}_{n \in \mathbb{N}}$ in X_ρ is said to be:
 - (i) ρ -convergent to x if $\rho(x_n - x) \rightarrow 0$ as $n \rightarrow \infty$.
 - (ii) ρ -Cauchy if $\rho(x_n - x_m) \rightarrow 0$ as $n, m \rightarrow \infty$.
- (b) X_ρ is ρ -complete if every ρ -Cauchy sequence is ρ -convergent.
- (c) A subset $B \subseteq X_\rho$ is said to be ρ -closed if $\{x_n\}_{n \in \mathbb{N}} \subset B$ with $x_n \rightarrow x$, then $x \in B$.
- (d) A subset $B \subseteq X_\rho$ is called ρ -bounded if

$$\delta_\rho(B) = \sup \{ \rho(x - y) : x, y \in B \} < \infty,$$

where $\delta_\rho(B)$ is called the ρ -diameter of B .

- (e) We say that ρ has the Fatou property if

$$\rho(x - y) \leq \liminf \rho(x_n - y_n),$$

whenever $\rho(x_n - x) \rightarrow 0$, $\rho(y_n - y) \rightarrow 0$ as $n \rightarrow \infty$.

- (f) ρ is said to satisfy the Δ_2 -condition if

$$\rho(x_n) \rightarrow 0 \quad \Rightarrow \quad \rho(2x_n) \rightarrow 0 \quad (\text{as } n \rightarrow \infty).$$

It is easy to check that for every modular ρ and $x, y \in X_\rho$,

- (1) $\rho(\alpha x) \leq \rho(\beta x)$ for each $\alpha, \beta \in \mathbb{R}^+$ with $\alpha \leq \beta$,
- (2) $\rho(x + y) \leq \rho(2x) + \rho(2y)$.

Now we recall some basic concepts about modular function spaces as formulated by Kozłowski [17].

Let Ω be a nonempty set and let Σ be a nontrivial σ -algebra of subsets of Ω . Let \mathcal{P} be a δ -ring of subsets of Σ such that $E \cap A \in \mathcal{P}$ for any $E \in \mathcal{P}$ and $A \in \Sigma$. Let us assume that there is an increasing sequence of sets $K_n \in \mathcal{P}$ such that $\Omega = \bigcup K_n$.

In other words, the family \mathcal{P} plays the role of δ -ring of subsets of finite measure. By \mathcal{E} we denote the linear space of all simple functions with supports from \mathcal{P} .

By \mathcal{M} we denote the space of all measurable functions, i.e., all functions $f : \Omega \rightarrow \mathbb{R}$ such that there exists a sequence $\{g_n\} \in \mathcal{E}$, $|g_n| \leq |f|$ and $g_n(w) \rightarrow f(w)$ for all $w \in \Omega$. By 1_A we denote the characteristic function of the set A .

Definition 1.5 A function $\rho : \mathcal{E} \times \Sigma \rightarrow [0, +\infty]$ is called a function modular if

- (i) $\rho(0, E) = 0$ for any $E \in \Sigma$;
- (ii) $\rho(f, E) \leq \rho(g, E)$ whenever $|f(w)| \leq |g(w)|$ for any $w \in \Omega, f, g \in \mathcal{E}$ and $E \in \Sigma$;
- (iii) $\rho(f, \cdot) : \Sigma \rightarrow [0, +\infty]$ is a σ -sub-additive measure for every $f \in \mathcal{E}$;
- (iv) $\rho(\alpha, A) \rightarrow 0$ as α decreases to 0 for every $A \in \mathcal{P}$, where $\rho(\alpha, A) = \rho(\alpha 1_A, A)$;
- (v) for any $\alpha > 0$, $\rho(\alpha, \cdot)$ is order continuous on \mathcal{P} , that is, $\rho(\alpha, A_n) \rightarrow 0$ if $\{A_n\} \in \mathcal{P}$ and decreases to \emptyset .

The definition of ρ is then extended to $f \in \mathcal{M}$ by

$$\rho(f, E) = \sup \{ \rho(g, E) : g \in \mathcal{E}, |g(w)| \leq |f(w)|, w \in \Omega \}.$$

For simplicity, we write $\rho(f)$ instead of $\rho(f, \Omega)$.

One can verify that the functional $\rho : \mathcal{M} \rightarrow [0, +\infty]$ is a modular in the sense of Definition 1.1. The modular space determined by ρ will be called a modular function space and will be denoted by L_ρ . Recall that

$$L_\rho = \left\{ f \in \mathcal{M} : \lim_{\alpha \rightarrow 0} \rho(\alpha f) = 0 \right\}.$$

Example 1.6 (1) The Orlicz modular is defined for every measurable real function f by the formula

$$\rho(f) = \int_{\mathbb{R}} \varphi(|f(t)|) d\mu(t),$$

where μ denotes the Lebesgue measure in \mathbb{R} and $\varphi : \mathbb{R} \rightarrow [0, \infty)$ is continuous. We also assume that $\varphi(u) = 0$ if and only if $u = 0$ and $\varphi(t) \rightarrow \infty$ as $t \rightarrow \infty$.

The modular space induced by the Orlicz modular, is a modular function space and is called the Orlicz space. (2) The Musielak-Orlicz modular spaces (see [2]).

Let

$$\rho(f) = \int_{\Omega} \varphi(\omega, |f(\omega)|) d\mu(\omega),$$

where μ is a σ -finite measure on Ω and $\varphi : \Omega \times \mathbb{R} \rightarrow [0, \infty)$ satisfy the following:

- (i) $\varphi(\omega, u)$ is a continuous even function of u , which is non-decreasing for $u > 0$, such that $\varphi(\omega, 0) = 0$, $\varphi(\omega, u) > 0$ for $u \neq 0$ and $\varphi(\omega, u) \rightarrow \infty$ as $u \rightarrow \infty$;
- (ii) $\varphi(\omega, u)$ is a measurable function of ω for each $u \in \mathbb{R}$;
- (iii) $\varphi(\omega, u)$ is a convex function of u for each $\omega \in \Omega$.

It is easy to check that ρ is a convex modular function and the corresponding modular space is called the Musielak-Orlicz space and is denoted by L^φ .

In the following we give some notions which will be used in the next sections.

Definition 1.7 (Khamsi [18]) Let C be a subset of a modular function space L_ρ . A mapping $T : C \rightarrow C$ is called ρ -strict contraction if there exists $\lambda < 1$ such that

$$\rho(Tf - Tg) \leq \lambda \rho(f - g)$$

for all $f, g \in C$.

Theorem 1.8 (Khamsi [18]) *Let C be a ρ -complete, ρ -bounded subset of L_ρ and let $T : C \rightarrow C$ be a ρ -strict contraction. Then T has a unique fixed point $z \in C$. Moreover, z is the ρ -limit of the iterate of any point in C under the action of T .*

Definition 1.9 (Taleb and Hanebaly [4]) *The function $u : I \rightarrow L^\varphi$, where $I = [0, A]$ for all $A > 0$, is said to be continuous at $t_0 \in I$ if for $t_n \in I$ and $t_n \rightarrow t_0$, then $\rho(u(t_n) - u(t)) \rightarrow 0$ as $n \rightarrow \infty$.*

If we consider the Musielak-Orlicz modular with Δ_2 -condition, then the continuity of u at t_0 is equivalent to

$$(t_n \rightarrow t_0) \Rightarrow \|u(t_n) - u(t_0)\|_\rho \rightarrow 0 \quad (\text{as } n \rightarrow \infty).$$

Let $C^\varphi = C(I, L^\varphi)$ be the space of all continuous mappings from $I = [0, A]$ into L^φ .

Proposition 1.10 (Taleb and Hanebaly [4]) *Suppose that the Musielak-Orlicz modular ρ satisfies Δ_2 -condition and $B \subset L^\varphi$ is a ρ -closed and convex subset of L^φ . For $a \geq 0$, let $\rho_a(u) = \sup\{e^{-at} \rho(u(t)) : t \in I\}$ for $u \in C^\varphi$, then*

- (1) *(C^φ, ρ_a) is a modular space, and ρ_a is a convex modular satisfying the Fatou property and the Δ_2 -condition;*
- (2) *C^φ is ρ_a -complete;*
- (3) *$C_0^\varphi = C(I, B)$ is a ρ_a -closed, convex subset of C^φ .*

2 Main results

Let X_ρ be a modular function space, C be a nonempty, ρ -complete and ρ -bounded subset of X_ρ , x_0 be an arbitrary point in C and let $\psi : [0, +\infty) \rightarrow [0, +\infty)$ be an increasing function vanishing with continuity at zero. Also, consider the vanishing sequence depending on $\alpha \geq 1$, $w_n(\alpha) = (\frac{\alpha}{n})^\alpha \sum_{k=1}^n \psi(\frac{\alpha}{k})$. Let $T : C \rightarrow C$ be a mapping. For notational purposes, we define $T^n(x)$, $x \in X_\rho$ and $n \in \{0, 1, 2, \dots\}$ inductively by $T^0(x) = x$ and $T^{n+1}(x) = T(T^n(x))$.

Theorem 2.1 *Let $\alpha \geq 1$, $\beta > 0$ and $k \geq 0$ be fixed constants. If the inequality*

$$\rho(Tx - Ty) \leq (1 - \epsilon)\rho(x - y) + \epsilon^\alpha \psi(\epsilon)(\rho(x - y) + k)^\beta \quad (2.1)$$

is satisfied for every $\epsilon \in [0, 1]$ and every $x, y \in C$, then T has a unique fixed point $z = T(z)$ which is the ρ -lim of the iterate of x_0 under the action of T .

Proof We first show existence. Let $\epsilon = 0$ in (2.1), thus we get

$$\rho(Tx - Ty) \leq \rho(x - y) \quad (2.2)$$

for all $x, y \in C$. We construct a sequence $\{x_n\}_{n=0}^\infty$ such that $x_n = T(x_{n-1})$ for all $n \in \mathbb{N}$. Now we claim $\{x_n\}$ is ρ -Cauchy sequence in C . By (2.1), (2.2) for all $m, n \in \mathbb{N}$, we have

$$\rho(x_{n+m} - x_n) \leq (1 - \epsilon)\rho(x_{n+m-1} - x_{n-1}) + \epsilon^\alpha \psi(\epsilon)(\rho(x_{n+m-1} - x_{n-1}) + k)^\beta. \quad (2.3)$$

Let $M := (\delta_\rho(C) + k)^\beta$. Since C is ρ -bounded, M is finite and from (2.3) we have

$$\rho(x_{n+m+1} - x_{n+1}) \leq (1 - \epsilon)\rho(x_{n+m} - x_n) + \epsilon^\alpha \psi(\epsilon)M.$$

Letting $\epsilon = 1 - (\frac{n}{n+1})^\alpha$, we have $\epsilon \leq \frac{\alpha}{n+1}$. Keeping in mind that ψ is an increasing function,

$$\begin{aligned}\rho(x_{n+m+1} - x_{n+1}) &\leq \frac{n^\alpha}{(n+1)^\alpha} \rho(x_{n+m} - x_n) + \frac{\alpha^\alpha}{(n+1)^\alpha} \psi\left(\frac{\alpha}{n+1}\right)M \\ \Rightarrow (n+1)^\alpha \rho(x_{n+m+1} - x_{n+1}) &\leq n^\alpha \rho(x_{n+m} - x_n) + \alpha^\alpha \psi\left(\frac{\alpha}{n+1}\right)M.\end{aligned}\quad (2.4)$$

Letting $r_n := n^\alpha \rho(x_{n+m} - x_n)$, we have from (2.4)

$$\begin{aligned}r_{n+1} &\leq r_n + \alpha^\alpha \psi\left(\frac{\alpha}{n+1}\right)M \\ &\leq r_{n-1} + \alpha^\alpha \psi\left(\frac{\alpha}{n}\right)M + \alpha^\alpha \psi\left(\frac{\alpha}{n+1}\right)M \\ &\vdots \\ &\leq r_0 + \alpha^\alpha M \sum_{k=1}^{n+1} \psi\left(\frac{\alpha}{k}\right) \\ &= \alpha^\alpha M \sum_{k=1}^{n+1} \psi\left(\frac{\alpha}{k}\right).\end{aligned}$$

Therefore

$$\rho(x_{n+m} - x_n) \leq \left(\frac{\alpha}{n}\right)^\alpha M \sum_{k=1}^n \psi\left(\frac{\alpha}{k}\right) = Mw_n(\alpha). \quad (2.5)$$

Taking limit as $n \rightarrow \infty$ from both sides of (2.5), we get $\rho(x_{n+m} - x_n) \rightarrow 0$ as $n \rightarrow \infty$. Then $\{x_n\}$ is ρ -Cauchy sequence in C . Since C is ρ -complete, there exists $z \in C$ such that $\rho(x_n - z) \rightarrow 0$ as $n \rightarrow \infty$. From (2.1) we get

$$\begin{aligned}\rho\left(\frac{Tz - z}{2}\right) &\leq \rho(Tz - x_n) + \rho(x_n - z) \\ &\leq (1 - \epsilon)\rho(z - x_{n-1}) + \epsilon^\alpha \psi(\epsilon)(\rho(z - x_{n-1}) + k)^\beta + \rho(x_n - z).\end{aligned}$$

Taking limit as $\epsilon \rightarrow 0$ afterwards as $n \rightarrow \infty$, we get

$$\rho\left(\frac{Tz - z}{2}\right) \leq \rho(z - x_{n-1}) + \rho(x_n - z) \rightarrow 0.$$

Then $Tz = z$. On the other hand, by (2.5), we have

$$\begin{aligned}\rho(z - T^n x_0) &= \rho(Tz - T^n x_0) = \rho(z - x_{n+1}) \\ &= \lim_{m \rightarrow \infty} \rho(x_{m+n+1} - x_{n+1}) \\ &\leq Mw_n(\alpha) \rightarrow 0 \quad (\text{as } n \rightarrow \infty).\end{aligned}$$

Thus z is the ρ -lim of the iterate of x_0 under the action of T .

To show uniqueness, we suppose that y is another fixed point of T . Then from (2.1) we have

$$\rho(z - y) = \rho(Tz - Ty) \leq (1 - \epsilon)\rho(z - y) + \epsilon^\alpha \psi(\epsilon)(\rho(z - y) + k)^\beta. \quad (2.6)$$

Then $\rho(z - y) \leq \epsilon^{\alpha-1} \psi(\epsilon)(\rho(z - y) + k)^\beta \rightarrow 0$ as $\epsilon \rightarrow 0$, therefore $z = y$.

If for each $\epsilon \in (0, 1]$ strict inequality occurs in (2.6), then

$$\epsilon^{1-\alpha} \rho(z - y) < \psi(\epsilon)(\rho(z - y) + k)^\beta.$$

Taking limit as $\epsilon \rightarrow 0$, we get contradiction unless $\rho(z - y) = 0$. \square

Remark 2.2 Theorem 2.1 is stronger than Theorem 1.8. Indeed, with the hypothesis of Theorem 1.8, if for each $f, g \in C$ and $\lambda \in (0, 1)$, we have

$$\rho(Tf - Tg) \leq \lambda \rho(f - g),$$

then by $\alpha = \beta = 1$, $k = 0$ and

$$\psi(\epsilon) = \left(\frac{\gamma^\gamma}{(1 + \gamma)^{1+\gamma}(1 - \lambda)^\gamma} \right) \epsilon^\gamma$$

for arbitrary $\gamma > 0$, we get

$$\rho(Tf - Tg) \leq (1 - \epsilon)\rho(f - g) + \epsilon \psi(\epsilon)\rho(f - g)$$

is satisfied for every $\epsilon \in [0, 1]$. Thus from Theorem 2.1, T has a unique fixed point z which is the ρ -lim of $T^n f_0$ for an arbitrary point f_0 in C .

3 Application

In this section, we study the existence of solution of the following integral equation:

$$u(t) = e^{-t} f_0 + \int_0^t e^{s-t} T u(s) ds, \quad (3.1)$$

where

(H₁) $T : B \rightarrow B$ is ρ -Lipschitz, i.e.,

$$\exists \kappa > 0, \quad \rho(Tu - Tv) \leq \kappa \rho(u - v) \quad (u, v \in B);$$

(H₂) B is a ρ -closed, ρ -bounded, convex subset of the Musielak-Orlicz space L^φ satisfying the Δ_2 -condition;

(H₃) $f_0 \in B$ is fixed.

Theorem 3.1 Under the conditions (H₁)-(H₃), for all $A > 0$, integral equation (3.1) has a solution $u \in C^\varphi = C([0, A], L^\varphi)$.

Proof Define the operator S on C_0^φ by

$$Su(t) = e^{-t}f_0 + \int_0^t e^{s-t}Tu(s)ds$$

for all $t \in I := [0, A]$.

1st step. First we show that $S : C_0^\varphi \rightarrow C_0^\varphi$. Let $u \in C_0^\varphi$ and $t_n, t_0 \in I$ for all $n \in \mathbb{N}$ with $t_n \rightarrow t_0$ as $n \rightarrow \infty$. We know u is ρ -continuous thus $\rho(u(t_n) - u(t_0)) \rightarrow 0$. From (H_1) we get $\rho(Tu(t_n) - Tu(t_0)) \rightarrow 0$ as $n \rightarrow \infty$, thus Tu is ρ -continuous at t_0 . By Δ_2 -condition Tu is $\|\cdot\|_\rho$ -continuous at t_0 , therefore Su is $\|\cdot\|_\rho$ -continuous at t_0 and consequently is ρ -continuous at t_0 . Also, we have

$$\int_0^t e^{s-t}Tu(s)ds \in \left(\int_0^t e^{s-t}ds\right)\overline{\text{co}}\{Tu(s); 0 \leq s \leq t\} \subseteq (1 - e^{-t})\overline{\text{co}}B,$$

where $\overline{\text{co}}B$ is a closed convex hull of B in $(L^\varphi, \|\cdot\|_\rho)$.

But B is convex and ρ -closed, then $\overline{\text{co}}B = B \subseteq \overline{B}_\rho = B$, hence

$$Su(t) \in e^{-t}B + (1 - e^{-t})B \subseteq B \quad (\forall t \in I).$$

2nd step. We show that C_0^φ is ρ_a -complete and ρ_a -bounded.

By Proposition 1.10, C_0^φ is a ρ_a -closed subset of ρ_a -complete space C^φ , hence C_0^φ is ρ_a -complete too.

Now let $u, v \in C_0^\varphi$. By 1st step $u(t), v(t) \in B$ for all $t \in I$, then

$$\rho_a(u - v) = \sup\{e^{-at}\rho(u(t) - v(t)); t \in I\} \leq \delta_\rho(B) < \infty,$$

therefore

$$\delta_{\rho_a}(C_0^\varphi) = \sup\{\rho_a(u - v); u, v \in C_0^\varphi\} < \infty.$$

3rd step. For $u, v \in C_0^\varphi$, we have

$$\rho_a(Su - Sv) \leq \kappa \left(\frac{1 - e^{-(1+a)A}}{1 + a} \right) \rho_a(u - v). \quad (3.2)$$

Let $w \in C^\varphi$ and $\{t_0, t_1, \dots, t_n\}$ be any division of $[0, t]$.

Now suppose

$$\sup\{|t_{i+1} - t_i|, i = 0, 1, \dots, n-1\} \rightarrow 0$$

as $n \rightarrow \infty$, then

$$\left\| \sum_{i=0}^{n-1} (t_{i+1} - t_i) e^{t_i-t} w(t_i) - \int_0^t e^{s-t} w(s) ds \right\|_\rho \rightarrow 0.$$

By Δ_2 -condition,

$$\rho \left(\sum_{i=0}^{n-1} (t_{i+1} - t_i) e^{t_i-t} w(t_i) - \int_0^t e^{s-t} w(s) ds \right) \rightarrow 0.$$

Using the Fatou property, we get

$$\rho\left(\int_0^t e^{s-t} w(s) ds\right) \leq \liminf \rho\left(\sum_{i=0}^{n-1} (t_{i+1} - t_i) e^{t_i-t} w(t_i)\right). \quad (3.3)$$

Furthermore,

$$\sum_{i=0}^{n-1} (t_{i+1} - t_i) e^{t_i-t} \leq \int_0^t e^{s-t} ds \leq 1 - e^{-t} \leq 1 - e^{-A} < 1.$$

By the convexity of ρ , we have

$$\begin{aligned} \rho\left(\sum_{i=0}^{n-1} (t_{i+1} - t_i) e^{t_i-t} w(t_i)\right) &\leq \sum_{i=0}^{n-1} (t_{i+1} - t_i) e^{t_i-t} \rho(w(t_i)) \\ &= \sum_{i=0}^{n-1} (t_{i+1} - t_i) e^{t_i-t} e^{at_i} e^{-at_i} \rho(w(t_i)) \\ &\leq \sum_{i=0}^{n-1} (t_{i+1} - t_i) e^{(1+a)t_i-t} \rho_a(w) \\ &\leq \left(\int_0^t e^{(1+a)s-t} ds\right) \rho_a(w). \end{aligned}$$

It follows from (3.3) that

$$\rho\left(\int_0^t e^{s-t} w(s) ds\right) \leq \left(\frac{e^{at} - e^{-t}}{1+a}\right) \rho_a(w). \quad (3.4)$$

On the other hand,

$$\rho(Su(t) - Sv(t)) = \rho\left(\int_0^t e^{s-t} (Tu(s) - Tv(s)) ds\right).$$

Thus by (3.4), we have

$$\rho(Su(t) - Sv(t)) \leq \left(\frac{e^{at} - e^{-t}}{1+a}\right) \rho_a(Tu - Tv),$$

since T is ρ -Lipschitz, we have

$$\begin{aligned} \rho(Su(t) - Sv(t)) &\leq \left(\frac{e^{at} - e^{-t}}{1+a}\right) \sup_{t \in I} e^{-at} \rho(Tu(t) - Tv(t)) \\ &\leq \left(\frac{e^{at} - e^{-t}}{1+a}\right) \kappa \sup_{t \in I} e^{-at} \rho(u(t) - v(t)) \\ &= \left(\frac{e^{at} - e^{-t}}{1+a}\right) \kappa \rho_a(u - v). \end{aligned}$$

Therefore

$$\begin{aligned} e^{-at} \rho(Su(t) - Sv(t)) &\leq \kappa \left(\frac{1 - e^{-(1+a)t}}{1+a} \right) \rho_a(u - v) \\ &\leq \kappa \left(\frac{1 - e^{-(1+a)A}}{1+a} \right) \rho_a(u - v) \end{aligned}$$

for all $t \in I$, which implies (3.2).

4th step. Let $\alpha = \beta = 1$, $k = 0$, $a > 0$ with

$$e^{-(1+a)A} > \frac{\kappa - (1+a)}{\kappa}.$$

If we have

$$\frac{\kappa(1 - e^{-(1+a)A})}{1+a} \leq (1 - \epsilon) + \epsilon^{1+\gamma} K$$

for all $\gamma > 0$, $\epsilon \in [0, 1]$ and a constant K , then (3.2) implies that the inequality (2.1) is satisfied by $\psi(\epsilon) = K\epsilon^\gamma$. To this end, we define

$$F(\epsilon) = (1 - \epsilon) + \epsilon^{1+\gamma} K - \frac{\kappa(1 - e^{-(1+a)A})}{1+a}.$$

Now imposing the conditions on F , which implies $0 \leq F(\epsilon)$ for all $\epsilon \in [0, 1]$, we obtain

$$K = \frac{\gamma^\gamma (1+a)^\gamma}{((1+a)(1+\gamma)^{1+\frac{1}{\gamma}} - \kappa(1+\gamma)^{1+\frac{1}{\gamma}}(1 - e^{-(1+a)A}))^\gamma}.$$

Therefore, from steps 1 to 4 and Theorem 2.1, we conclude the existence of a fixed point of S which is the solution of integral equation (3.1). \square

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

All authors contributed equally. All authors read and approved the final manuscript.

Author details

¹Department of Mathematics, Science and Research Branch, Islamic Azad University, Tehran, Iran. ²Department of Mathematics, Semnan University, P.O. Box 35195-363, Semnan, Iran. ³Department of Mathematics Education and the RINS, Gyeongsang National University, Chinju, 660-701, Korea. ⁴Department of Mathematics and Computer Sciences, Amirkabir University of Technology, Hafez Ave., P.O. Box 15914, Tehran, Iran.

Received: 28 November 2012 Accepted: 17 May 2013 Published: 31 October 2013

References

1. Nakano, H: *Modular Semi-Ordered Spaces*. Tokyo Mathematical Book Series. Maruzen, Tokyo (1950)
2. Musielak, J, Orlicz, W: On modular spaces. *Stud. Math.* **18**, 49-65 (1959)
3. Khamsi, MA, Kozłowski, WM, Reich, S: Fixed point theory in modular function spaces. *Nonlinear Anal.* **14**(11), 935-953 (1990)
4. Taleb, A, Hanebaly, E: A fixed point theorem and its application to integral equations in modular function spaces. *Proc. Am. Math. Soc.* **128**(2), 419-426 (2000)
5. Dhompongs, S, Domínguez Benavides, T, Kaewcharoen, A, Panyanak, B: Fixed point theorems for multivalued mappings in modular function spaces. *Sci. Math. Jpn.* **63**(2), 161-169 (2006)
6. Kutbi, MA, Latif, A: Fixed points of multivalued maps in modular function spaces. *Fixed Point Theory Appl.* **2009**, 786357 (2009). doi:10.1155/2009/786357

7. Khamsi, MA, Latif, A, Al-Sulami, H: KKM and KY fan theorems in modular function spaces. *Fixed Point Theory Appl.* **2011**, 57 (2011). doi:10.1186/1687-1812-2011-57
8. Farajzadeh, AP, Mohammadi, MB, Noor, MA: Fixed point theorems in modular spaces. *Math. Commun.* **16**, 13-20 (2011)
9. Hussain, N, Khamsi, MA, Latif, A: Banach operator pairs and common fixed points in modular function spaces. *Fixed Point Theory Appl.* **2011**, 75 (2011). doi:10.1186/1687-1812-2011-75
10. Abbas, M, Khan, SH, Razani, A: Fixed point theorems of expansive type mappings in modular function spaces. *Fixed Point Theory* **12**(2), 235-240 (2011)
11. Kozłowski, WM: Advancements in fixed point theory in modular function spaces. *Arab. J. Math.* **1**, 477-494 (2012). doi:10.1007/s40065-012-0051-0
12. Al-Mezel, SA, Al-Roqi, A, Khamsi, MA: One-local retract and common fixed point in modular function spaces. *Fixed Point Theory Appl.* **2012**, 109 (2012). doi:10.1186/1687-1812-2012-109
13. Mongkolkeha, C, Kumam, P: Some fixed point results for generalized weak contraction mappings in modular spaces. *Int. J. Anal.* **2013**, 247378 (2013). doi:10.1155/2013/247378
14. Bin Dehaish, BA, Kozłowski, WM: Fixed point iteration processes for asymptotic pointwise nonexpansive mapping in modular function spaces. *Fixed Point Theory Appl.* **2012**, 118 (2012). doi:10.1186/1687-1812-2012-118
15. Pata, V: A fixed point theorem in metric spaces. *J. Fixed Point Theory Appl.* **10**, 299-305 (2011). doi:10.1007/s11784-011-0060-1
16. Musielak, J: *Orlicz Spaces and Modular Spaces*. Lecture Notes in Math., vol. 1034. Springer, Berlin (1983)
17. Kozłowski, WM: *Modular Function Spaces*. Monographs and Textbooks in Pure and Applied Mathematics, vol. 122. Dekker, New York (1988)
18. Khamsi, MA: A convexity property in modular function spaces. *Math. Jpn.* **44**(2), 269-279 (1996)

doi:10.1186/1687-1812-2013-239

Cite this article as: Paknazar et al.: A Pata-type fixed point theorem in modular spaces with application. *Fixed Point Theory and Applications* 2013 **2013**:239.

Submit your manuscript to a SpringerOpen[®] journal and benefit from:

- Convenient online submission
- Rigorous peer review
- Immediate publication on acceptance
- Open access: articles freely available online
- High visibility within the field
- Retaining the copyright to your article

Submit your next manuscript at ► springeropen.com